

OXFORD CAMBRIDGE AND RSA EXAMINATIONS

**Advanced Subsidiary General Certificate of Education
Advanced General Certificate of Education**

MATHEMATICS

2640

Mechanics 4

Friday

28 MAY 2004

Afternoon

1 hour 20 minutes

Additional materials:

Answer booklet

Graph paper

List of Formulae (MF8)

TIME 1 hour 20 minutes

INSTRUCTIONS TO CANDIDATES

- Write your Name, Centre Number and Candidate Number in the spaces provided on the answer booklet.
- Answer **all** the questions.
- Give non-exact numerical answers correct to 3 significant figures unless a different degree of accuracy is specified in the question or is clearly appropriate.
- Where a numerical value for the acceleration due to gravity is needed, use 9.8 m s^{-2} .
- You are permitted to use a graphic calculator in this paper.

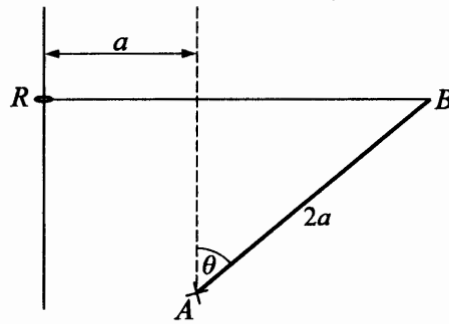
INFORMATION FOR CANDIDATES

- The number of marks is given in brackets [] at the end of each question or part question.
- The total number of marks for this paper is 60.
- Questions carrying smaller numbers of marks are printed earlier in the paper, and questions carrying larger numbers of marks later in the paper.
- **You are reminded of the need for clear presentation in your answers.**

This question paper consists of 3 printed pages and 1 blank page.

- 1 Two flywheels P and Q are rotating, in opposite directions, about the same fixed axis. The angular speed of P is 25 rad s^{-1} and the angular speed of Q is 30 rad s^{-1} . The flywheels lock together, and after this they both rotate with angular speed 10 rad s^{-1} in the direction in which P was originally rotating. The moment of inertia of P about the axis is 0.64 kg m^2 . Find the moment of inertia of Q about the axis. [4]
- 2 A uniform rectangular lamina has mass m and sides of length $3a$ and $4a$, and rotates freely about a fixed horizontal axis. The axis is perpendicular to the lamina and passes through a corner. The lamina makes small oscillations in its own plane, as a compound pendulum.
- (i) Find the moment of inertia of the lamina about the axis. [3]
- (ii) Find the approximate period of the small oscillations. [3]
- 3 The region between the curve $y = x\sqrt{3-x}$ and the x -axis for $0 \leq x \leq 3$ is rotated through 2π radians about the x -axis to form a uniform solid of revolution. Find the x -coordinate of the centre of mass of this solid. [6]
- 4 A uniform solid sphere, of mass 14 kg and radius 0.25 m , is rotating about a fixed axis which is a diameter of the sphere. A couple of constant moment 4.2 N m about the axis, acting in the direction of rotation, is applied to the sphere.
- (i) Find the angular acceleration of the sphere. [3]
- During a time interval of 30 seconds the sphere rotates through 7500 radians.
- (ii) Find the angular speed of the sphere at the start of the time interval. [2]
- (iii) Find the angular speed of the sphere at the end of the time interval. [2]
- (iv) Find the work done by the couple during the time interval. [2]
- 5 Two aircraft A and B are flying horizontally at the same height. A has constant velocity 240 m s^{-1} in the direction with bearing 025° , and B has constant velocity 185 m s^{-1} in the direction with bearing 310° .
- (i) Find the magnitude and direction of the velocity of A relative to B . [5]
- Initially A is 4500 m due west of B . For the instant during the subsequent motion when A and B are closest together, find
- (ii) the distance between A and B , [3]
- (iii) the bearing of A from B . [2]

6



A uniform rod AB , of mass m and length $2a$, is free to rotate in a vertical plane about a fixed horizontal axis through A . A light elastic string has natural length a and modulus of elasticity mg ; one end is attached to B and the other end is attached to a light ring R which can slide along a smooth vertical wire. The wire is in the same vertical plane as AB , and is at a distance a from A . The rod AB makes an angle θ with the upward vertical, where $0 < \theta < \frac{1}{2}\pi$ (see diagram).

(i) Give a reason why the string RB is always horizontal. [1]

(ii) By considering potential energy, find the value of θ for which the system is in equilibrium. [6]

(iii) Determine whether this position of equilibrium is stable or unstable. [4]

7 A uniform rod AB has mass m and length $2a$. The point P on the rod is such that $AP = \frac{2}{3}a$.

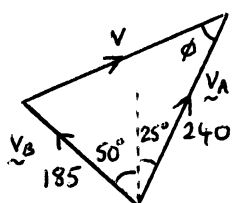
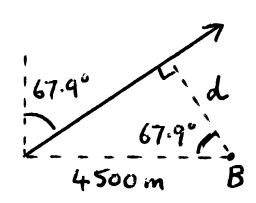
(i) Prove by integration that the moment of inertia of the rod about an axis through P perpendicular to AB is $\frac{4}{9}ma^2$. [4]

The axis through P is fixed and horizontal, and the rod can rotate without resistance in a vertical plane about this axis. The rod is released from rest in a horizontal position. Find, in terms of m and g ,

(ii) the force acting on the rod at P immediately after the release of the rod, [5]

(iii) the force acting on the rod at P at an instant in the subsequent motion when B is vertically below P . [5]

1	$0.64 \times 25 - I \times 30 = (0.64 + I) \times 10$ $I = 0.24 \text{ kg m}^2$	M1 A1A1 A1 4	Use of angular momentum For LHS and RHS
2 (i)	$I = \frac{4}{3}m\left(\frac{3}{2}a\right)^2 + \frac{4}{3}m(2a)^2$ $= \frac{25}{3}ma^2$	B1 M1 A1 3	For either term Use of perpendicular axes rule
	OR $I = \frac{1}{3}m\left\{\left(\frac{3}{2}a\right)^2 + (2a)^2\right\} + m\left(\frac{5}{2}a\right)^2$ $= \frac{25}{3}ma^2$	B1 M1 A1	For $\frac{1}{3}m\left\{\left(\frac{3}{2}a\right)^2 + (2a)^2\right\}$ Use of parallel axes rule
(ii)	Period is $2\pi\sqrt{\frac{I}{mgh}}$ $= 2\pi\sqrt{\frac{\frac{25}{3}ma^2}{mg\frac{5}{2}a}}$ $= 2\pi\sqrt{\frac{10a}{3g}}$	M1 A1 ft A1 3	or $(-)\ mgh \sin \theta = I\ddot{\theta}$ or $-mg\left(\frac{5}{2}a\right)\theta \approx \frac{25}{3}ma^2\ddot{\theta}$
3	$\int \pi xy^2 dx = \int_0^3 \pi x^3(3-x) dx$ $= \pi \left[\frac{3}{4}x^4 - \frac{1}{5}x^5 \right]_0^3 \quad (= 12.15\pi)$ $\int \pi y^2 dx = \int_0^3 \pi x^2(3-x) dx$ $= \pi \left[x^3 - \frac{1}{4}x^4 \right]_0^3 \quad (= 6.75\pi)$ $\bar{x} = \frac{12.15\pi}{6.75\pi}$ $= 1.8$	M1 A1 M1 A1 M1 A1 6	(π may be omitted throughout) Dependent on previous M1M1
4 (i)	$I = \frac{2}{5} \times 14 \times 0.25^2 \quad (= 0.35)$ $4.2 = I\alpha$ $\alpha = 12 \text{ rad s}^{-2}$	B1 M1 A1 3	
(ii)	$\theta = \omega_1 t + \frac{1}{2}\alpha t^2; \quad 7500 = \omega_1 \times 30 + \frac{1}{2} \times 12 \times 30^2$ $\omega_1 = 70 \text{ rad s}^{-1}$	M1 A1 ft 2	Ft $250 - 15\alpha$
(iii)	$\omega_2 = \omega_1 + \alpha t; \quad \omega_2 = 70 + 12 \times 30$ $\omega_2 = 430 \text{ rad s}^{-1}$	M1 A1 ft 2	Ft $250 + 15\alpha$
(iv)	Work done is $L\theta = 4.2 \times 7500$ $= 31500 \text{ J}$	M1 A1 2	Or $\frac{1}{2}I(\omega_2^2 - \omega_1^2)$

<p>5 (i)</p>	 $v^2 = 240^2 + 185^2 - 2 \times 240 \times 185 \cos 75$ $v = 262 \text{ m s}^{-1}$ $\frac{\sin \phi}{185} = \frac{\sin 75}{262.4}$ $\phi = 42.9^\circ$ <p>Bearing is $25 + \phi = 067.9^\circ$</p>	<p>B1</p> <p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p>	<p>Velocity triangle If wrong triangle used, then B0 M1A0 M1A0 for equivalent work Full ft in (ii) and (iii)</p> <p>Accept $68^\circ, 67.8^\circ$ 5 Allow other clearly stated descriptions of direction</p>
	<p>OR $\mathbf{v} = \begin{pmatrix} 240 \sin 25 \\ 240 \cos 25 \end{pmatrix} - \begin{pmatrix} 185 \sin 310 \\ 185 \cos 310 \end{pmatrix}$</p> $= \begin{pmatrix} 243 \\ 98.6 \end{pmatrix}$ $v = \sqrt{243^2 + 98.6^2} = 262$ <p>Bearing is $\tan^{-1} \frac{243}{98.6} = 67.9^\circ$</p>	<p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p> <p>A1</p>	<p>Finding magnitude or angle</p>
<p>(ii)</p>	<p>As viewed from B</p>  $d = 4500 \cos 67.9$ $= 1690 \text{ m}$	<p>M1</p> <p>M1</p> <p>A1 ft</p>	<p>Relative displacement diagram</p> <p>Ft from bearing in (i) 3</p>
<p>(iii)</p>	<p>Bearing is $270 + 67.9 = 338^\circ$</p> <p>OR $\overrightarrow{BA} = \begin{pmatrix} 243t - 4500 \\ 98.6t \end{pmatrix}$</p> $BA^2 = (243t - 4500)^2 + (98.6t)^2 \text{ is minimum}$ <p>when $t = \frac{4500 \times 243}{243^2 + 98.6^2} (= 15.9)$</p> <p>Then $BA = 1690$</p>	<p>M1</p> <p>A1 ft</p> <p>M1</p> <p>A1 ft</p>	<p>Ft from relative velocity in (i) 2 SR B1 ft for 158°</p> <p>Ft from relative velocity in (i)</p>

<p>6 (i)</p>	<p>e.g. R has no weight / mass There is no friction There is no vertical force at R String has minimum length / elastic energy</p>	<p>B1 1</p>	<p>For any one contributory reason</p>
<p>(ii)</p>	$V = \frac{1}{2} \left(\frac{mg}{a} \right) (2a \sin \theta)^2 + mga \cos \theta$ $= mga(2 \sin^2 \theta + \cos \theta)$ $\frac{dV}{d\theta} = mga(4 \sin \theta \cos \theta - \sin \theta)$ <p>For equilibrium, $mga \sin \theta(4 \cos \theta - 1) = 0$ $\theta = 1.32$ (or 75.5°)</p>	<p>B2 B1 ft B1 ft M1 A1 6</p>	<p>Give B1 for correct EE or PE</p> <p>Diffn of $\sin^2 \theta$ (or $\cos^2 \theta$) Diffn of $\cos \theta$ (or $\sin \theta$)</p> <p>Allow $\cos^{-1} \frac{1}{4}$, 76° <i>Ignore $\theta = 0$ if stated</i> <i>Marks can be awarded in (iii) if not earned in (ii)</i> <i>SR If done by taking moments,</i> <i>MIA1 for</i> $\frac{mg(2a \sin \theta)}{a} (2a \cos \theta) = mg(a \sin \theta)$ <i>A1 for $\theta = 1.32$ (Max 3 out of 6)</i> <i>These marks may only replace all other marks in (ii)</i></p>
<p>(iii)</p>	$\frac{d^2V}{d\theta^2} = mga \cos \theta(4 \cos \theta - 1) - 4mga \sin^2 \theta$ <p>When $\cos \theta = \frac{1}{4}$,</p> $\frac{d^2V}{d\theta^2} = -4mga \sin^2 \theta (= -\frac{15}{4}mga) < 0$ <p>Equilibrium is unstable</p>	<p>B2 ft M1 A1 4</p>	<p>Give B1 if just one error <i>Only B1 ft if work is simpler</i></p> <p>Fully correct working only</p>
	<p>OR When $\theta < 1.32$, $\frac{dV}{d\theta} > 0$</p> <p>When $\theta > 1.32$, $\frac{dV}{d\theta} < 0$</p> <p>V has a maximum Equilibrium is unstable</p>	<p>B1 ft B1 ft M1 A1</p>	<p>Fully correct working, and convincing demonstration of signs above</p>

<p>7 (i)</p>	$I = \sum (\rho \delta x) x^2$ $= \int_{-\frac{2}{3}a}^{\frac{4}{3}a} \frac{m}{2a} x^2 dx$ $= \left[\frac{mx^3}{6a} \right]_{-\frac{2}{3}a}^{\frac{4}{3}a} = \frac{32}{81} ma^2 + \frac{4}{81} ma^2$ $= \frac{4}{9} ma^2$	<p>M1 A1 M1 A1 (ag)</p> <p style="text-align: right;">4</p>	<p><i>Dependent on previous M1</i></p>
<p>(ii)</p>	<p>OR $I_G = \sum (\rho \delta x) x^2 = \int_{-a}^a \frac{m}{2a} x^2 dx$ M1A1</p> $I = \frac{1}{6} ma^2 + \frac{1}{6} ma^2 + m(\frac{1}{3}a)^2$ M1 $= \frac{4}{9} ma^2$ A1 (ag)	<p>M1A1 M1 A1 (ag)</p>	<p>Or $2 \int_0^a \frac{m}{2a} x^2 dx$</p> <p><i>Dependent on previous M1</i></p>
<p>(iii)</p>	$mg(\frac{1}{3}a) = (\frac{4}{9}ma^2)\alpha$ $\alpha = \frac{3g}{4a}$ $mg - R = m(\frac{1}{3}a)\alpha$ $mg - R = \frac{1}{4}mg$ $R = \frac{3}{4}mg \text{ vertically upwards}$	<p>M1 A1 M1 A1 ft A1</p> <p style="text-align: right;">5</p>	<p>Use of $L = I\alpha$</p> <p>For force = $m(\frac{1}{3}a)\alpha$</p> <p>Direction must be indicated</p>
<p>(iii)</p>	$\frac{1}{2}(\frac{4}{9}ma^2)\omega^2 = mg(\frac{1}{3}a)$ $\omega^2 = \frac{3g}{2a}$ $S - mg = m(\frac{1}{3}a)\omega^2$ $S - mg = \frac{1}{2}mg$ $S = \frac{3}{2}mg \text{ vertically upwards}$	<p>M1 A1 M1 A1 ft A1</p> <p style="text-align: right;">5</p>	<p>Use of $\frac{1}{2}I\omega^2$</p> <p>For force = $m(\frac{1}{3}a)\omega^2$</p> <p>Direction must be indicated</p>
<p>Alternative for (ii) and (iii)</p>	$\ddot{\theta} = \frac{3g \cos \theta}{4a}$ M1A1 $\dot{\theta}^2 = \frac{3g \sin \theta}{2a}$ M1A1 $mg \cos \theta - Y = m(\frac{1}{3}a) \frac{3g \cos \theta}{4a}$ M1A1 ft $Y = \frac{3}{4}mg \cos \theta$ $X - mg \sin \theta = m(\frac{1}{3}a) \frac{3g \sin \theta}{2a}$ M1A1 ft $X = \frac{3}{2}mg \sin \theta$ When $\theta = 0$, $X = 0$, $Y = \frac{3}{4}mg$ A1 When $\theta = \frac{1}{2}\pi$, $X = \frac{3}{2}mg$, $Y = 0$ A1	<p>M1A1 M1A1 M1A1 ft A1 A1</p>	<p>(θ measured from horizontal X is radial component Y is transverse component)</p>